

# A modified Li-He's variational principle for plasma

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1369

Received 29 June 2019  
Revised 29 June 2019  
Accepted 30 June 2019

## Abstract

**Purpose** – It is extremely difficult to establish a variational principle for plasma. Kalaawy obtained a variational principle by using the semi-inverse method in 2016, and Li and He suggested a modification in 2017. This paper aims to search for a generalized variational formulation with a free parameter.

**Design/methodology/approach** – The semi-inverse method is used by suitable construction of a trial functional with some free parameters.

**Findings** – A modification of Li-He's variational principle with a free parameter is obtained.

**Originality/value** – This paper suggests a new approach to construction of a trial-functional with some free parameters.

**Keywords** Variational theory, Semi-inverse method, Burger equation, Plasma, Editorial

**Paper type** Research paper

## 1. Introduction

In 2016, Kalaawy obtained the following equation for plasma (El-Kalaawy, 2016):

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} \left[ \frac{2}{3} Au^{3/2} - C \frac{\partial u}{\partial x} \right] = 0 \quad (1)$$

and derived a variational principle by using the semi-inverse method (He, 2004; He, 2017; Wu and He, 2018) through introducing two special functions.

In 2017, Li and He found another variational principle, which reads (Li and He, 2017):

$$J_{Li-He}(u, \Phi) = \iint \left\{ \frac{1}{2} \frac{\partial \Phi}{\partial x} \frac{\partial \Phi}{\partial t} + \frac{2}{3} Au^{3/2} \frac{\partial \Phi}{\partial x} - \frac{1}{2} C \left( \frac{\partial \Phi}{\partial x} \right)^2 - \frac{2}{5} Au^{5/2} \right\} dx dt \quad (2)$$

where  $\Phi$  satisfies the following relations:

$$\frac{\partial \Phi}{\partial x} = u \quad (3)$$

$$\frac{\partial \Phi}{\partial t} = -\frac{2}{3} Au^{3/2} + C \frac{\partial u}{\partial x} \quad (4)$$

## 2. General variational principle with a free parameter

The semi-inverse method is widely used to search for variational principles directly from governing equations (El-Kalaawy, 2016; El-Kalaawy, 2017; Biswas *et al.*, 2017). By the



semi-inverse method (He, 2004; He, 2017; Wu and He, 2018), we can construct a trial-functional in the form:

$$J(u, \Phi) = \iint \left\{ u \frac{\partial \Phi}{\partial t} + \left[ \frac{2}{3} Au^{3/2} - C \frac{\partial u}{\partial x} \right] \frac{\partial \Phi}{\partial x} + F \right\} dxdt \quad (5)$$

where  $F$  is a known function of  $u$  and its derivative, however we cannot identify  $F$ , so equation (5) has to be modified as:

$$J_{New}(u, \Phi) = \iint \left\{ mu \frac{\partial \Phi}{\partial t} + n \frac{\partial \Phi}{\partial x} \frac{\partial \Phi}{\partial t} + aAu^{1/2} \left( \frac{\partial \Phi}{\partial x} \right)^2 + bAu^{3/2} \frac{\partial \Phi}{\partial x} - C \frac{\partial u}{\partial x} \frac{\partial \Phi}{\partial x} + F \right\} dxdt \quad (6)$$

where  $m, n, a$  and  $b$  are constants.

The stationary conditions of equation (6) are as follows:

$$-m \frac{\partial u}{\partial t} - 2n \frac{\partial^2 \Phi}{\partial x \partial t} - \frac{\partial}{\partial x} \left[ 2aAu^{1/2} \frac{\partial \Phi}{\partial x} + bAu^{3/2} - C \frac{\partial u}{\partial x} \right] = 0 \quad (7)$$

and

$$m \frac{\partial \Phi}{\partial t} + \frac{1}{2} aAu^{-1/2} \left( \frac{\partial \Phi}{\partial x} \right)^2 + \frac{3}{2} bAu^{1/2} \frac{\partial \Phi}{\partial x} + C \frac{\partial}{\partial x} \left( \frac{\partial \Phi}{\partial x} \right) + \frac{\delta F}{\delta u} = 0 \quad (8)$$

In view of equations (3) and (4), we have:

$$-(m + 2n) \frac{\partial u}{\partial t} - \frac{\partial}{\partial x} \left[ (2a + b)Au^{3/2} - C \frac{\partial u}{\partial x} \right] = 0 \quad (9)$$

$$mC \frac{\partial u}{\partial x} + \left( \frac{1}{2}a + \frac{3}{2}b - \frac{2}{3}m \right) Au^{3/2} + C \frac{\partial u}{\partial x} + \frac{\delta F}{\delta u} = 0 \quad (10)$$

Equation (9) should be equivalent to equation (1), this requires:

$$2a + b = 1 \quad (11)$$

$$m + 2n = 1 \quad (12)$$

To identify  $F$  in equation (10), we set:

$$m = -1 \quad (13)$$

Equation (10) becomes:

$$\left( \frac{1}{2}a + \frac{3}{2}b + \frac{2}{3} \right) Au^{3/2} + \frac{\delta F}{\delta u} = 0 \quad (14)$$

From equation (14), F can be identified as:

$$F = -\frac{2}{5} \left( \frac{1}{2}a + \frac{3}{2}b + \frac{2}{3} \right) Au^{5/2} = -\frac{2}{5} \left( \frac{13}{6} - \frac{5}{2}a \right) Au^{5/2} \quad (15)$$

We, therefore, obtain the following variational principle:

$$J_{New}(u, \Phi) = \iint \left\{ \frac{\partial \Phi}{\partial x} \frac{\partial \Phi}{\partial t} - u \frac{\partial \Phi}{\partial t} + aAu^{1/2} \left( \frac{\partial \Phi}{\partial x} \right)^2 + (1-2a)Au^{3/2} \frac{\partial \Phi}{\partial x} - C \frac{\partial u}{\partial x} \frac{\partial \Phi}{\partial x} - \frac{2}{5} \left( \frac{13}{6} - \frac{5}{2}a \right) Au^{5/2} \right\} dxdt$$

where  $a$  is a free parameter.

### 3. Conclusion

In this paper, we suggest a general construction of a trial functional with some parameters. The semi-inverse method is a powerful tool to establish variational principles from the governing equations. The variational principle is a foundation of the variational iteration method (Anjum and He, 2019; He, 2006), which is now widely applied in fractional calculus (Baleanu *et al.*, 2018; Dogan Durgun and Konuralp, 2018; Inc *et al.*, 2018; Jafari *et al.*, 2018; Wang *et al.*, 2018).

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#### **About the author**

Ji-Huan He is an expert on Nonlinear Science and Nanotechnology. He is the owner of some famous analytical methods, such as the semi-inverse method, the variational iteration method, the homotopy perturbation method, the exp-function method and He's frequency formulation. He has published more than 390 articles with an *h*-index of 66. Ji-Huan He can be contacted at: [hejihuan@suda.edu.cn](mailto:hejihuan@suda.edu.cn)